BIMA Memoranda Series #9

SYNTHESISED BEAMS AND INTERFEROMETER ARRAY RESPONSE TO EXTENDED STRUCTURE Melvyn Wright, 1-May-91

ABSTRACT

Large scale structure is poorly represented in images made from interferometer observations because of missing low spatial frequencies. In this memo we plot the BIMA array beam patterns for the standard arrays, and tabulate the response as a function of the source size. We briefly review the methods used to estimate the integrated flux density for an extended source.

ARRAY CONFIGURATIONS FOR 3 ANTENNAS

The standard BIMA array configurations were designed to provide approximately circular beams over a wide range of declinations, and with a low sidelobe level using equal weighting for each sampled uv point (natural weighting). The sidelobe level can be reduced, and the resolution improved, by weighting the uvdata to obtain a more uniform sampling in the uv plane. The SNR and the array response to extended structure are both degraded by using uniform weighting. Table 1 lists the standard arrays. Some attention has been paid to minimizing the number, and changes in direction, of the antenna moves.

| | T | ABLE 1 | - BIMA | ARRAYS | FOR 3 | ANTEN | NAS. | |
|--|---|--|--|--------|----------------------------|-------------------------------------|-------------------------------------|------------------------------------|
| | a-array | | | | | b | -array | |
| a1 a2 a3 a4 a5 a6 a7 | 40E 500W 240W 400E 400E 500E | 500N 100N 260N 200N 240W 380W 500W | 580N 320N 380N 380N 0N 580N 580N | | b1 b2 b3 b4 b5 | 40E 180E 100W 240W 180E | 260N 100N 140N 40N 100W | 320N 200N 200N 140N 0N |
| WH 2010 | | | | | c0 c1 c2 c3 | 15E 40W 40W 40E | 15W 80E 40N 60N | 20N 0N 100N 140N |

SYNTHESISED BEAMS

The synthesised beams were made with equal weighting for each sampled uv point (natural weighting), and with an elevation limit of 15 degrees. The FWHM of Gaussian fits at 100GHz are listed in Table 2. The a-array consists of the first 5 configurations. The a+ array consists of all 7 configurations. The ab-array is the b-array together with the al configuration (6 configurations) to improve the resolution at low declinations. The b+c array is the combined b-array and c-array (9 configurations). The synthesised beams are plotted in Figures 1-8.

| | TABLE 2 - SYNT | HESISED BEAMWIDT | H FOR BIMA ARRAY | S |
|-------|--------------------|-------------------|--------------------|--------------------|
| | | | | |
| | | Declination | | |
| array | -30 | - 5 | 20 | 45 |
| a+ | 5.5×2.0 | 2.9×2.1 | 2.4×2.1 | 2.4×2.0 |
| a | 6.8×2.4 | 3.8×2.5 | 3.1×2.7 | 3.2×2.5 |
| ab | 9.8×5.4 | 6.9×5.5 | 6.0×5.5 | 6.2×5.1 |
| b | 13.8×5.0 | 7.3×5.4 | 6.1×5.6 | 6.3×5.1 |
| b+c | 16.9×7.9 | 10.2×8.5 | 9.1×8.4 | 9.4×7.9 |
| C | 33.3×15.8 | 17.6 x 16.6 | 17.2×14.3 | 17.7×14.1 |

RESPONSE TO EXTENDED STRUCTURE

In an attempt to quantify the interferometer array response to extended structure I made a series of Gaussian models with fwhm from 5 to 60 arcsec and convolved them by the synthesised beam. The Gaussians were truncated at 10% to provide models with a realistic source distribution and a finite overall size equal to twice the fwhm. The ratio of the integrated flux in the convolved image (units: Jy/beam) and in the initial model (units: Jy/pixel) give a measure of the effective beam area (in pixels) as a function of source size. This is analogous to the "main beam coupling factor" for single dish antennas. An important difference is that an aperture synthesis beam pattern has negative sidelobes and can give a negative effective beam area, or coupling factor, when observing large scale structure. This can lead to large negative values on an aperture synthesis image. A similar analysis for disk models can be obtained from a radial integration of the beam in elliptical annuli.

Table 3 gives the effective area (in pixels) as a function of source size. Table 3 shows how the effective area decreases as the source size increases for the b-array, i.e. the synthesised beam is poorly coupled to extended sources. The negative values indicate that a 20" fwhm Gaussian is completely resolved except at declination -30 where the beam is more extended in declination. For the bc-array the effective beam area at first increases for larger sources. This is similar to the typical single dish response which has a larger main beam efficiency, or coupling factor, for larger source sizes. However, when the source size exceeds the fringe spacing of the lowest spatial frequency, then the source is rapidly resolved with increasing size. Table 3 also lists the effective beam area, or clean beam oversampling factor, cbof, for a Gaussian beam with the beamwidths given in Table 2. For a Gaussian beam cbof = pi*bmaj*bmin/(4log(2)), where bmaj and bmin are the fwhm beamwidths. We have chosen the pixel size as 1 arcsec so that the units in Table 3 are also the beam area in arcsec**2.

| ינו דכו איווי | 3 - | EFFECTIVE | DEAM | ABEA | ΔC | Δ | FINCTION | OF | SOURCE | SIZE |
|---------------|-----|-------------|------|------|----|-----|----------|-----|--------|------|
| TADLL | J - | PER POTTAGE | DEAN | AUDA | MO | 4.7 | FONCITON | Or. | DOOMCE | STAB |

| | THOLIS O | петпс | 11111 11111 | .i likuli li | 5 11 10110111 | on or boome | 2 0100 | |
|--|----------|--|--|------------------------------------|-------------------------------|-------------|--------|--|
| | | | declina | | | | | |
| | | -30 | -5 | 20 | 45 | | | |
| a-array cbof 5 | | 18 27 | 11 14 | 9 10 | 9 1 <u>1</u> | | | |
| 10 | | 53 | 9 | 3 | 5 | | | |
| 15 | | 52 | | _ | - | | | |
| 20 | | 40 | **** | _ | | | | |
| b-array cbof 5 10 15 20 | | 78 52 105 159 78 | 45 39 47 23 | 39 35 33 9 | 36 34 34 8 | | | |
| bc-array cbof 10 20 30 40 50 | | 134 192 338 281 177 66 6 | 87 133 169 163 126 77 47 | 76 117 156 155 75 - | 74 115 144 131 45 | | | |

INTEGRATED FLUX DENSITY OF AN EXTENDED SOURCE.

It is often quite difficult to obtain reliable estimates for the integrated flux density of an extended source from an image made with missing spatial frequencies. Several methods are commonly used.

1) Integration of a cleaned image.

If the source distribution is confined to some well defined portion of the image, then an estimate of the integrated flux density can be obtained by summing over the source, and dividing the integral by the beam oversampling factor. The beam oversampling factor is well defined on a deconvolved, or "cleaned" image, which has been convolved by a Gaussian beam. The integrated flux density is obtained by summing the pixel values over the area of interest and dividing by cbof for the Gaussian beam. However, for the original synthesised images, the effective beam area of the synthesised beam is a function of the source size and the cbof is not so well defined. A clean image, obtained by deconvolving the synthesised beam, and convolving by a clean beam may distort the integrated flux. The clean beam is usually estimated from a Gaussian fit to the synthesised beam, but the integral over the synthesised beam will depend on the size of the source. If the Gaussian clean beam has a larger effective beam area than the synthesised beam, then the clean, convolved image will have a higher integrated flux than the synthesised map, and vice-versa.

2) Integration of a deconvolved image.

A better estimate may be obtained by integrating a deconvolved image, or model of the source distribution which has units of Jy/pixel. This estimate must be corrected if some flux remains in the residual image (residual = map - model*beam; here * denotes convolution). Note that the residual image has a beam oversampling factor appropriate to the synthesised beam.

3) Correction for missing short spacing uvdata.

For interferometer observations where the zero spacing is missing, the integral over the whole image is zero, thus the positive source distribution must be balanced elsewhere on the image by negative regions. An antenna array usually samples the uvdata over some region with an outer boundary, which determines the resolution, and an inner boundary defined by the closest antenna spacings. If we think of this as a uniformly sampled region with a hole in the center, then the missing information on the synthesised map is the source distribution convolved by a beam corresponding to the hole. Thus a compact source appears to sit in a shallow basin whose size corresponds to the spatial frequency of the hole. A better estimate of the integrated flux from the source is obtained by correcting for the zero level around the image of the source. To some extent the clean algorithm fills in the hole when the deconvolved image is convolved by a Gaussian beam which has a higher effective area (better coupling to extended source structure) than the synthesised beam. This extrapolation may not be reliable.

4) Total flux estimates from uvdata.

It is sometimes possible to estimate the "zero spacing flux" by plotting the measured visibility flux density versus the uv-spacing, and extrapolating to zero spacing. It is usually necessary to average the uvdata to obtain sufficient signal to noise. If the source contains extended structure which is unsampled by the uvdata, then the extrapolation will be unreliable.

5) Spatial filtering to remove sidelobes from undersampled source structure.

Large negative values on a synthesised image can result from partially sampled extended structure. A cleaner image of the compact source structure may result by omitting the low spatial frequencies which are poorly sampling the extended structure. One of the advantages of interferometer observations is that the

uvdata may be selected to filter out confusing structure.

6) Including estimates of large scale structure from other data.

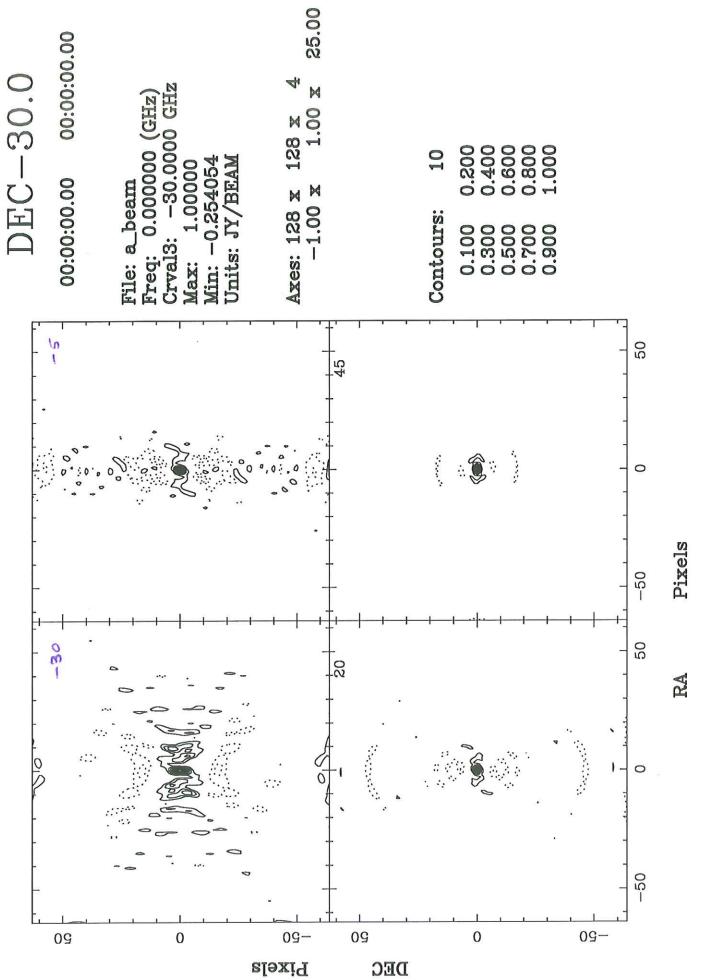
A better image is obtained by including the missing low spatial frequencies in the image. These can be obtained either from more compact interferometer configurations, or from a single dish image. This is discused elswhere.

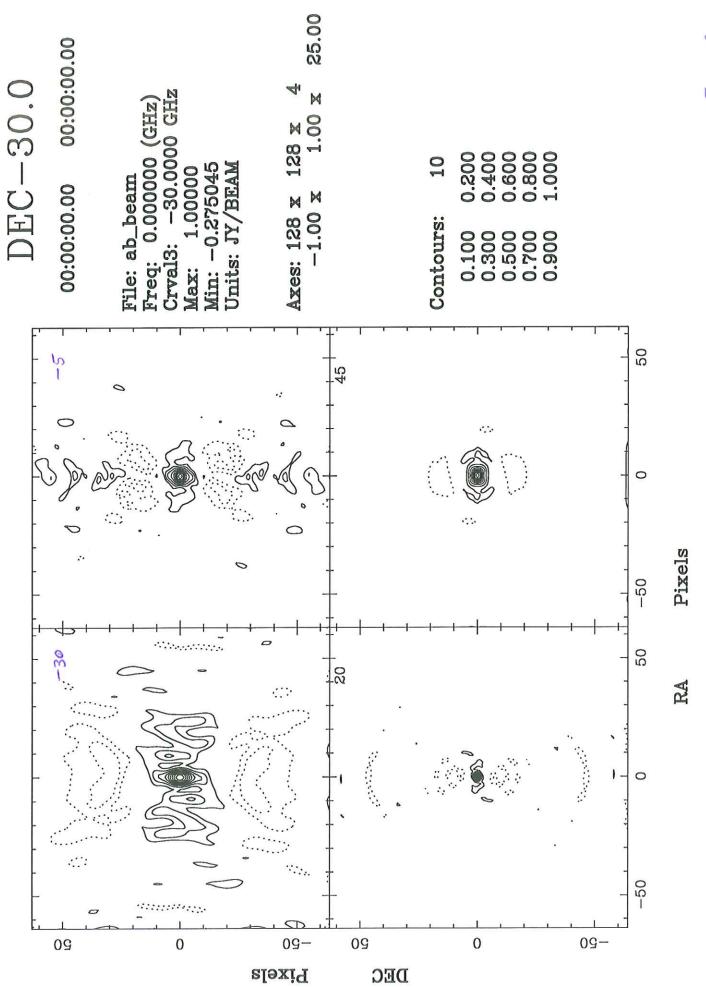
FIGURES

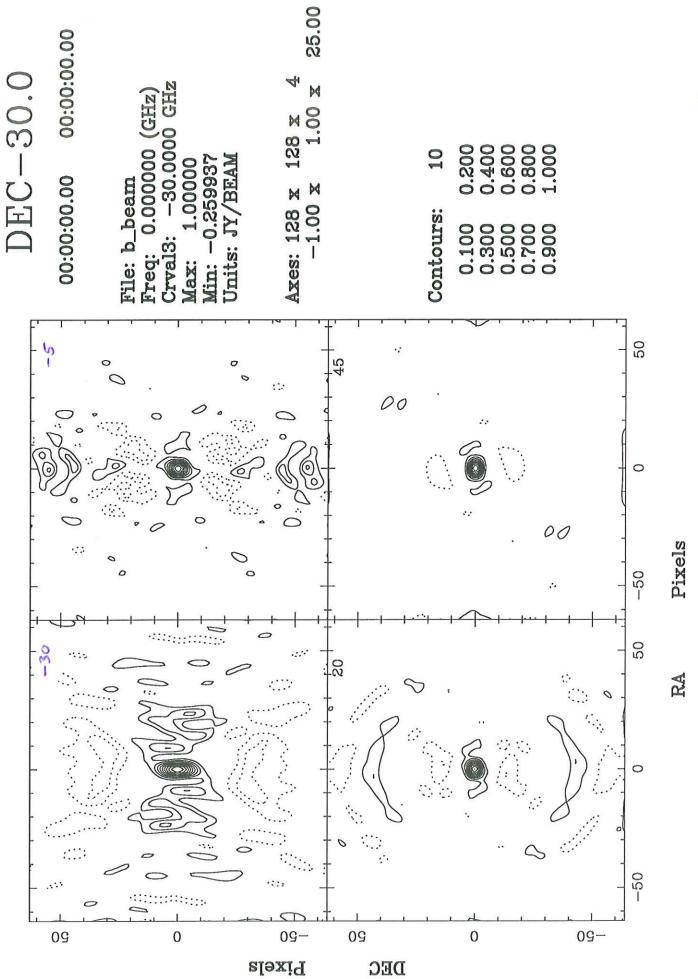
- Figure 1 Synthesised beams for a-array for declinations -30 -5 20 and 45.

 The a-array consists of the first 5 configurations. The contours are plotted at intervals of 10%. Negative contours are shown dotted.
- Figure 2 Synthesised beams for ab-array. Declinations and contours as above. The ab-array is the b-array + the al configuration to improve the resolution at low declinations. (6 configurations)
- Figure 3 Synthesised beams for b-array. Declinations and contours as above.
- Figure 4 Synthesised beams for b+c arrays. Declinations and contours as above.

 The b+c array is the combined b-array and c-array (9 configurations).
- Figure 5 Synthesised beams for c-array. Declinations and contours as above.
- Figure 6 Synthesised beams for a+ array. Declinations and contours as above. The a+ array consists of the 7 configurations listed in Table 1.
- Figure 7 Synthesised beams for a+b array. Declinations and contours as above. This uses the standard a+b arrays (10 configurations)
- Figure 8 Synthesised beams for a+b+c array. Declinations and contours as above. This uses the standard a+b+c arrays (14 configurations)







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